

Amendments to the Specification:

Please replace the paragraph beginning on page 9, line 11 with the following amended paragraph:

In the meantime, the PCB 12 carried by the conveyer 10 can be freely moved within the work area WP. Further, the moving member 20 which the PCB 12 is seated thereon is moved through the predefined movement route within the work area [[UP]] WP, for example, in a direction of the arrow in Fig. 3. The movement route is to be previously defined by the user, and can thus be varied by the user as necessary.

Please replace the paragraph beginning on page 9, line 24 with the following amended paragraph:

At first, the PCB 12 carried by the conveyer 10 is seated on the moving member 20. The moving member 20 carrying the PCB 12, which can be moved in predetermined direction, is then moved in a direction set by the user. For example, assuming that left lower point is taken as reference point in Fig. 3, if the PCB 12 is moved toward the left lower point, the head units 50 coupled to a plurality of Y-frames 40 hold the electronic components, and the components are then mounted on the PCB 12 after a vision unit 60 identified the electronic components. As the PCB 12 moves in a direction, 1->2->3->4, indicated by the arrow in Fig. 3, the head units 50 coupled to the Y-frames [[50]] 40 also move corresponding thereto, thereby sequentially

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mounting the electronic components on the PCB 12 after being identified by the vision units 60.

Please replace the paragraph beginning on page 13, line 2 with the following amended paragraph:

However, the present embodiment of the invention generally uses both first and second conveyers 70, 72 to thereby reduce the process time by individual process for the PCB 12 without the overlapping processes for the PCBs 12. Thus, this results in an improvement of the throughput. Further, the PCBs 12 are continuously provided to the first conveyer 70 in a predetermined interval, and therefore a [[wast]] waste of extra time can be reduced.